



**MP450 Controller**  
for Cut-to-Length Machines

***Technical Reference &  
Installation Guide***

Copyright © 2008 – AMS Controls, Inc. All rights reserved.

The information contained in this document is proprietary to AMS Controls, Inc., and is not to be reproduced in any form without the specific written authorization of AMS Controls, Inc.

AMS Controls, Inc. reserves the right to change the contents of this manual without customer notice or permission. The procedures described in this handbook must be performed only by trained, certified industrial electricians in accordance with local, state, federal, and NEC codes and regulations. While AMS Controls has taken all reasonable care to develop safe procedures, it accepts no responsibility for misprints, or for injuries, damages, death, or destruction to persons or equipment caused as a result of not closely following these instructions. For specific controller questions, contact AMS Controls Inc.

The most current version of this manual is always available at:  
[www.amscontrols.com/files/manuals/default.asp](http://www.amscontrols.com/files/manuals/default.asp)

AMS Controls, Inc.  
12180 Prichard Farm Road  
Maryland Heights, MO 63043

314.344.3144 – 1-800-334-5213 (US & Canada) – fax: 314.344.9996 – [info@amscontrols.com](mailto:info@amscontrols.com)

[www.amscontrols.com](http://www.amscontrols.com)

# Table of Contents

<b>TABLE OF CONTENTS</b> .....	<b>I</b>
<b>CHAPTER 1: INTRODUCTION</b> .....	<b>3</b>
<b>OVERVIEW</b> .....	<b>3</b>
<i>Features</i> .....	3
<b>CHAPTER 2: INSTALLATION SPECIFICS</b> .....	<b>4</b>
<b>MECHANICAL DETAILS</b> .....	<b>4</b>
<i>Dimensional Drawing</i> .....	4
<i>Cutout Drawing</i> .....	5
<b>ELECTRICAL DETAILS</b> .....	<b>5</b>
<i>Specifications</i> .....	5
Power.....	5
Inputs.....	6
Outputs .....	6
Encoder.....	6
Environmental .....	6
<i>Pin Assignments and Descriptions</i> .....	7
J301 .....	7
J401 .....	8
<b>SAMPLE INTERFACE DRAWING</b> .....	<b>9</b>
<b>SOFTWARE CONFIGURATION</b> .....	<b>10</b>
<i>Setup Screen</i> .....	10
Navigate the Setup Screen.....	10
Setup Parameters .....	11
<b>CHAPTER 3: OPERATIONAL REFERENCE</b> .....	<b>12</b>
<b>POSITIONING CONTROL</b> .....	<b>12</b>
<i>Speed Logic Table</i> .....	12
<i>Speed Diagram for Two-Speed Positioning</i> .....	13
<i>Adaptive Stopping Compensation</i> .....	13

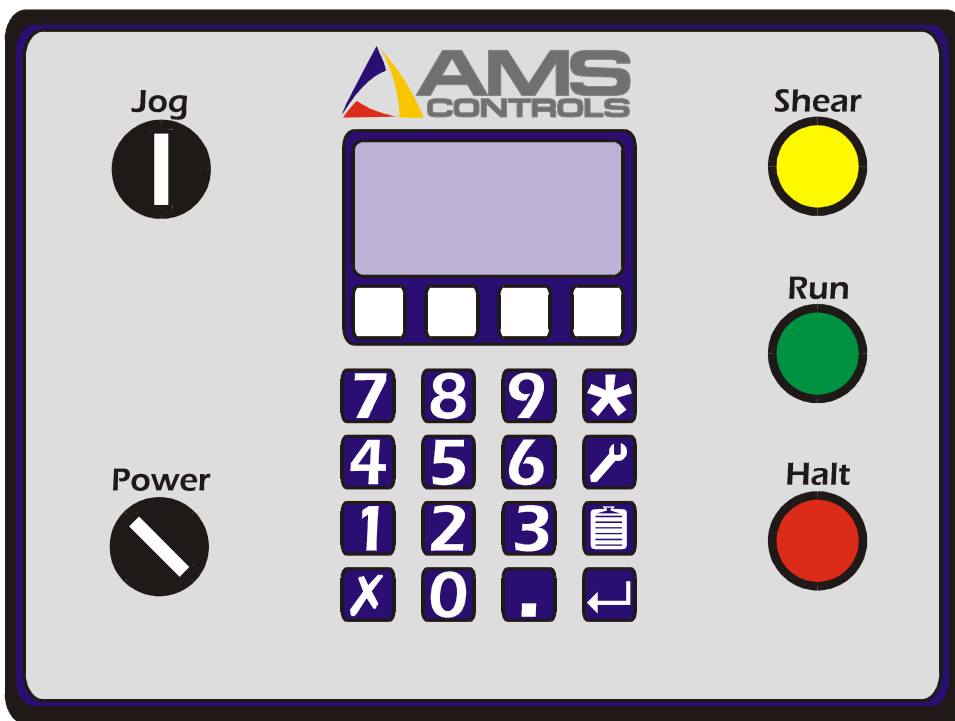


# Chapter 1: Introduction

---

## Overview

The AMS Controls MP450 is an industrial controller used to control cut-to-length machinery. Figure 1 shows the front panel of the MP450.



*Figure 1: AMS Controls MP450 Controller*

## Features

The MP450 controller's features include:

- Accurate length control
- Simple programming
- Easy calibration

# Chapter 2: Installation Specifics

## Mechanical Details

### Dimensional Drawing

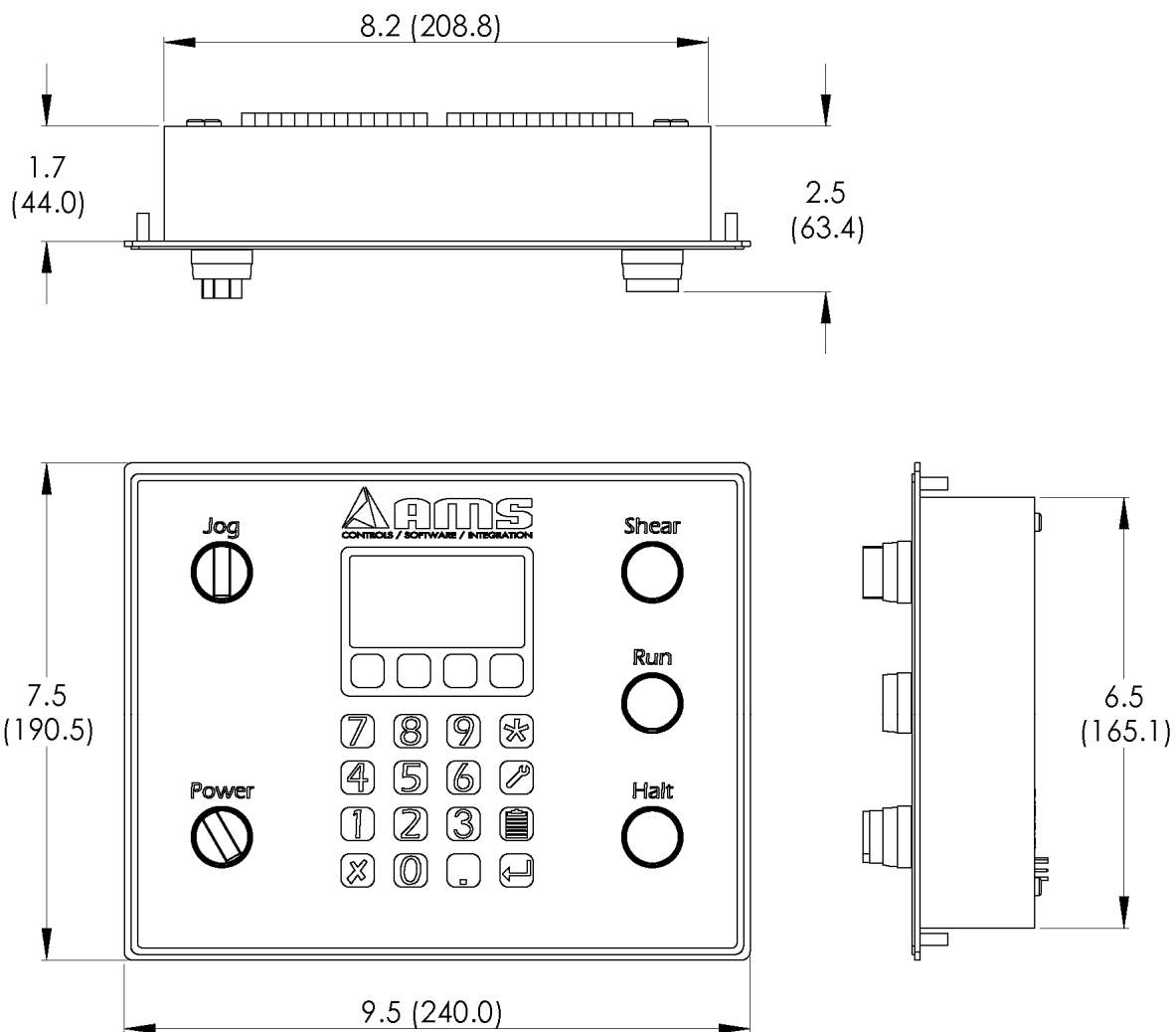


Figure 2: MP450 Dimensional Drawing

## Cutout Drawing

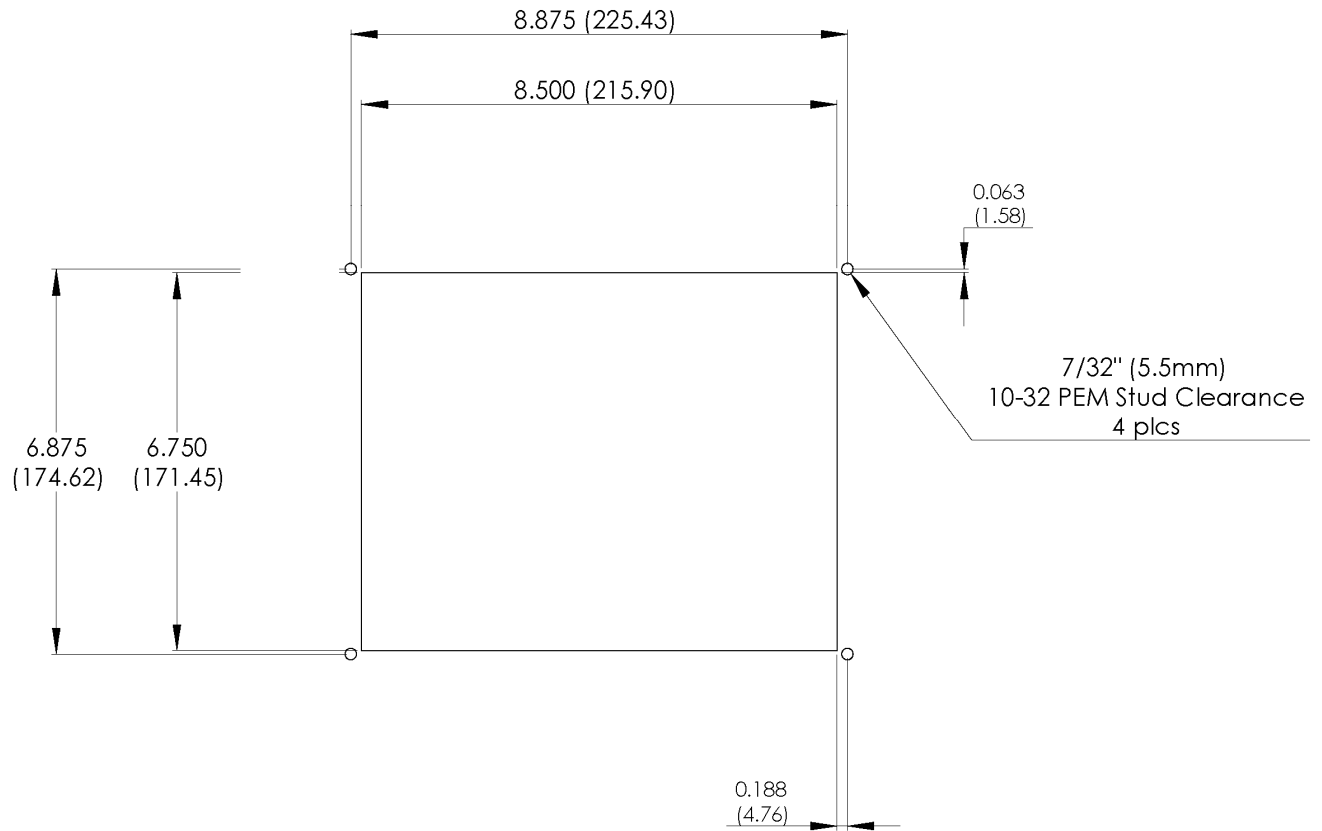


Figure 3: MP450 Cutout Drawing

## Electrical Details

### Specifications

#### Power

Supply voltage	24VDC (+/- 20%)
Supply current	400mA + Outputs
Max. inrush current	2A

Inputs

<b>Type</b>	Sourcing
<b>Voltage</b>	24VDC
<b>Input resistance</b>	1.8 K $\Omega$
<b>“ON” voltage</b>	13.4 VDC
<b>Optical Isolation</b>	2500V

Outputs

<b>Type</b>	Sourcing
<b>Voltage</b>	24 VDC
<b>Continuous Current</b>	3A
<b>Optical Isolation</b>	2500V

Encoder

<b>Supply voltage</b>	5 VDC
<b>Supply current</b>	100mA
<b>Type</b>	Quadrature, differential (RS485)
<b>Max. frequency</b>	50 KHz
<b>Optical Isolation</b>	2500V

Environmental

<b>Min. operating temp. (ambient)</b>	-20C (-4F)
<b>Max. operating temp. (ambient)</b>	65C (150F)
<b>Min. storage temp.</b>	-30C (-22F)
<b>Max storage temp.</b>	85C (185F)



***Pin Assignments and Descriptions******J301***

<b>Pin</b>	<b>Function</b>	<b>Assignment/Notes</b>
<b>1</b>	I/O Ground	6A maximum
<b>2</b>	Output 1	Fast
<b>3</b>	Output 2	Shear Down
<b>4</b>	Output 3	Reverse
<b>5</b>	Output 4	Shear Up
<b>6</b>	Output 5	Slow
<b>7</b>	I/O Ground	6A maximum
<b>8</b>	I/O V (+24V)	
<b>9</b>	Input 1	Shear Up
<b>10</b>	Input 2	Not Used
<b>11</b>	Input 3	Shear Down
<b>12</b>	Input 4	Remote Run
<b>13</b>	Input 5	Not Used
<b>14</b>	I/O V (+24V)	

J401

<b>Pin</b>	<b>Function</b>	<b>Notes</b>
<b>1</b>	RS485 2B+	Unused
<b>2</b>	RS485 2A-	
<b>3</b>	RS485 1A+	For firmware updates
<b>4</b>	RS485 1B-	
<b>5</b>	Encoder A+	
<b>6</b>	Encoder A-	
<b>7</b>	Encoder B+	
<b>8</b>	Encoder B-	
<b>9</b>	Encoder +5V	
<b>10</b>	Encoder Ground	
<b>11</b>	Power +VDC	
<b>12</b>	Power Ground	
<b>13</b>	Power switch contact A Panel Switch	20A maximum
<b>14</b>	Power switch contact B Panel Switch	20A maximum

# Sample Interface Drawing

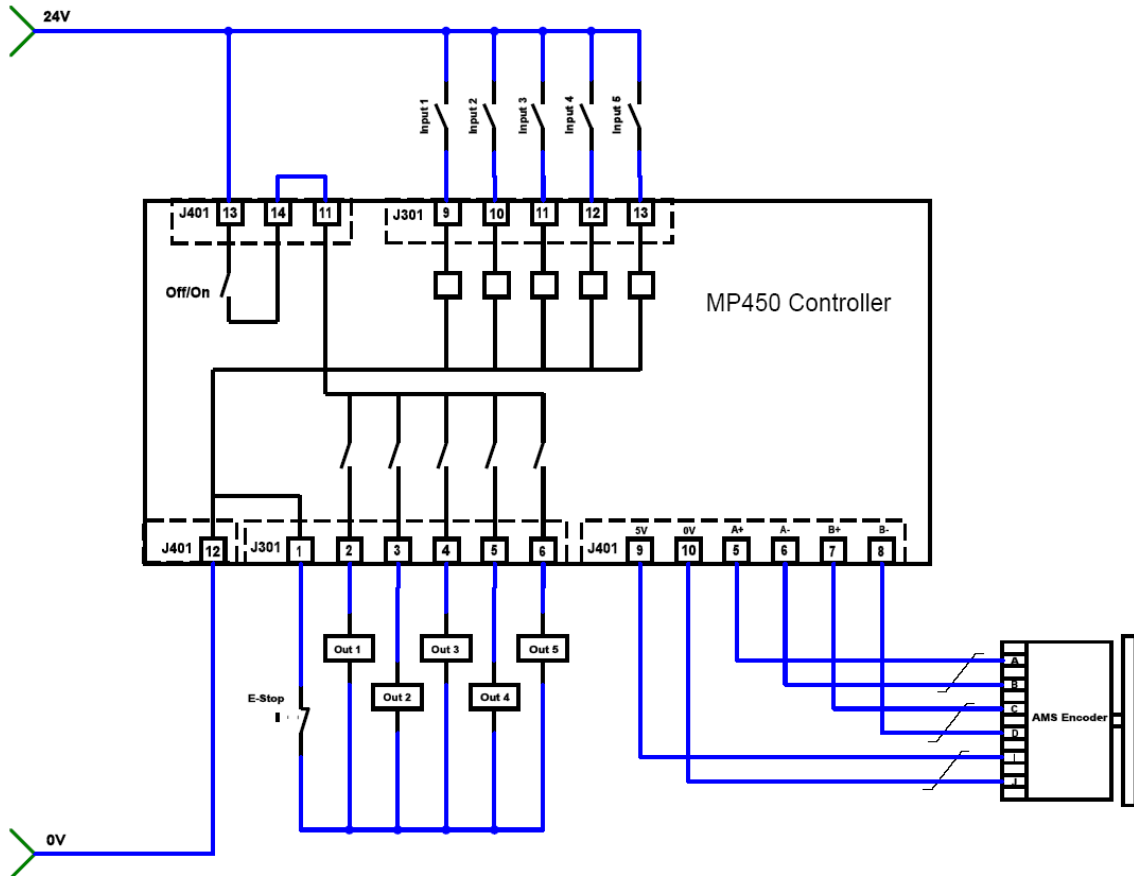


Figure 4: MP450 Sample Interface Drawing

## Software Configuration

### Setup Screen

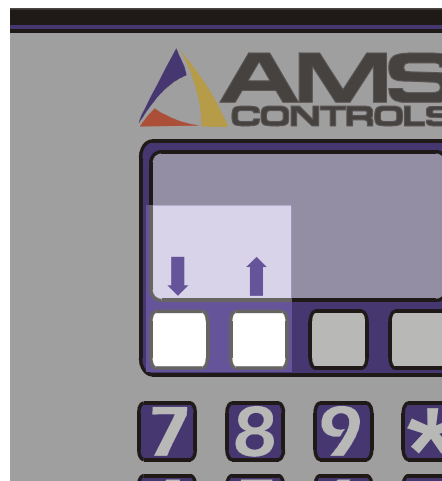
Use the Setup screen to change the display units, encoder direction and slow distance.

To enter the setup screen,



1. Power up the system.
2. While the startup screen displays, press [9]. The Setup screen displays.

### Navigate the Setup Screen

- Use the Up and Down soft keys (white keys just below the display, see Figure 5) to navigate from item to item.



**Figure 5: AMS Controls MP450 Controller front panel  
(Up and Down Soft Keys highlighted)**

- Press a number key to change a selected setting temporarily, causing the field to blink.
- Press [Enter]  to save the new setting and move to the next setup item, or [Clear]  to restore the value to its original value.
- Press the Up (↑) or Down (↓) arrow keys while a field is blinking to restore its original value and move to the next item.

## Setup Parameters

 **Note:** These parameters retain their value while the machine is powered off.

### *Display Units*

The display unit setting enables the operator to choose between viewing the part length in either feet and inches or metric millimeters.

### *Encoder Direction*

The encoder direction allows the operator to change the direction of the encoder without modifying the machine wiring.

Changing this setting is necessary, for example, if the material position is shown to be moving backwards on the controller while the material is actually moving forwards. You would use this parameter, then, to reverse the encoder direction for the controller so it can register forward and backward movement correctly.


### *Slow Distance*

The distance that the controller feeds in slow speed before stopping for the cut operation.

The accuracy of a two-speed stopping control system depends on a stable slow speed. Through experimentation, it is possible to find a value that provides a good balance between accuracy and productivity.

If this parameter is set to zero, the controller operates in single speed mode, where it decelerates from fast speed to zero velocity. While this may increase the production of the machine, typically it is difficult to achieve good part length accuracy in this mode.

# Chapter 3: Operational Reference

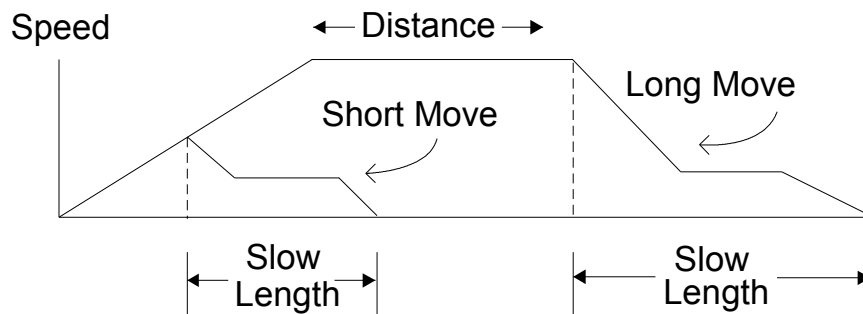
 **Note:** For details on operating a machine with the MP450 Controller, see the MP450 Operator Manual.

## Positioning Control

### Speed Logic Table

Function		Output			
		<i>Slow</i>	<i>Fast</i>	<i>Reverse</i>	
<i>Jog Forward</i>		Off	On	Off	<b>Manual</b>
<i>Jog Reverse</i>		On	Off	On	
<b>2-Speed Mode</b>	<i>Run Fast</i>	Off	On	Off	<b>Automatic</b>
	<i>Run Slow</i>	On	Off	Off	
<b>Single Speed Mode</b>	<i>Run</i>	Off	On	Off	

## Speed Diagram for Two-Speed Positioning



**Figure 6: Speed Profile with Adaptive Stopping**

### Adaptive Stopping Compensation

*Adaptive stopping compensation* is a feature that enables the controller to account for changes in the amount of time required to bring moving material to a stop.

With a stopping control system, the controller must turn off the motion output before the desired target position is reached. The material then decelerates to a stop and is hopefully within the desired tolerance.

The MP450 constantly monitors the deceleration rate of the machine and makes slight adjustments to the time at which the motion output is turned off. This constant monitoring and adjustment is an important feature for machines that have stopping dynamics that change over time. This is especially an issue with hydraulics-based motion control where the temperature of the oil can affect the stopping behavior of the machine.